

DAMSEL - A Data Model Storage Library for Exascale Science

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Outline

- Project Team
- Motivation
- Damsel I/O Library
- Usecases: FLASH, GCRM
- Proposed API and implementation, Data layout (In Progress)



Project Team

- **Northwestern University:** Alok Choudhary, Wei-keng Liao, Kui Gao, Saba Sehrish, Chen Jin, William Hendrix
- **Argonne National Laboratory:** Rob Ross, Rob Latham, Tim Tautges, Venkat Vishwanath
- **The HDF Group:** Quincey Koziol, Gerd Herber
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1 Motivation

- Computational and Data Model Motifs
- Existing I/O Libraries
- Goals



Computational Model Motifs

Table 1: The expanded list of Computational Motifs (Dwarfs). Here, we have identified data models used in the motifs and provided illustrative examples. Some codes employ more than one motif. This project focuses on the top six (blue).

Motif	Data Model/ Data Structure	Examples
Dense Linear Algebra	a	BLAS, LAPACK, ScaLAPACK, Matlab, 
Sparse Linear Algebra	f	OSKI, SuperLU, SpMV
Spectral Methods	a	FFT, Nek5000 (Nuclear Energy)
N-Body Methods	b, e, j	Molecular Dynamics, NN-Search
Structured Grids (+ AMR)	a, b, c	FLASH (Astrophysics), Chombo-based codes
Unstructured Grids (+ AMR)	c	UNIC, Phasta, SELFE numerical tsunami models
Monte Carlo, MapReduce	a-l	GFMC, EM, POV-Ray
Combinational Logic	g, i	RSA encryption, FastBit
Graph Traversal	f, h	 Boost Graph Library (BGL), C4.5
Dynamic Programming	a	Smith-Waterman
String Searches	d, e	BLAST, HMMER
Backtrack and Branch-and-Bound	f, i, g	Clique, Kernel regression
Probabilistic Graphical Models	h, k	BBN, HMM, CRF
Finite State Machines	l	Collision detection

a–Multidimensional array, e.g., dense matrix in 2D; **b**–Point- or region-based quadtree, octree, compressed octree, or hypertree; **c**–Lattice model; **d**–Suffix tree, suffix array; **e**–R-tree, B-tree, X-tree, and their variants; **f**–Sparse matrix, e.g., block compressed sparse row (BCSR); **g**–Bitmap index, bitvector; **h**–Direct Acyclic Graph (DAG); **i**–Hash table, grid file; **j**–K-d tree; **k**–Junction tree; **l**–Transition table, Petri net.



Data Model Motifs

Data Models Exemplars			
Exemplar	Domain	Computational Motif	Data Model Motif
FLASH	Astrophysics	v	Structured Adaptive
MADNESS	Quantum Chemistry	i, iii, iv, vi	Unstructured Adaptive
Nek5000	Nuclear Energy	iii	Structured Adaptive
PHASTA	CFD	ii, vi	Unstructured Adaptive
S3D	Combustion	v	Structured Regular
UNIC	Neutron Transport	ii, vi	Unstructured Regular

i—Dense Linear Algebra; ii—Sparse Linear Algebra; iii—Spectral Methods; iv—N-Body Methods; v—Structured Grids (+ AMR); vi—Unstructured Grids (+ AMR).

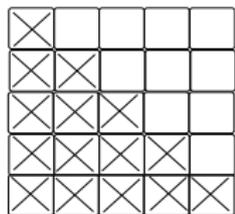


Existing I/O Libraries

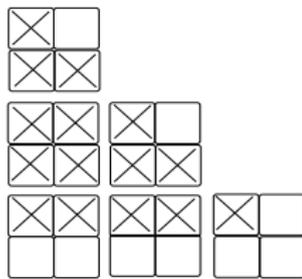
- Storage data models developed in the 1990s; Network Common Data Format (netCDF) and Hierarchical Data Format (HDF)
- I/O library interfaces still based on low-level vectors of variables
- Lack of support for sophisticated data models, e.g. AMR, unstructured Grids, Geodesic grid, etc
- Require too much work at application level to achieve close to peak I/O performance



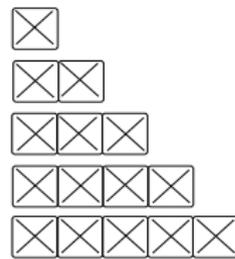
Example: Lower Triangle Matrix



netCDF: fixed dimensions



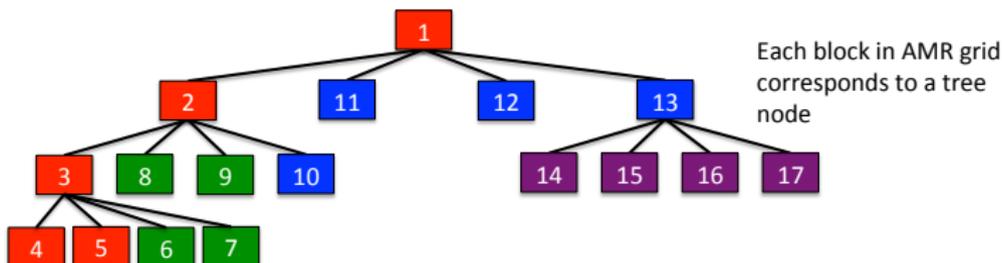
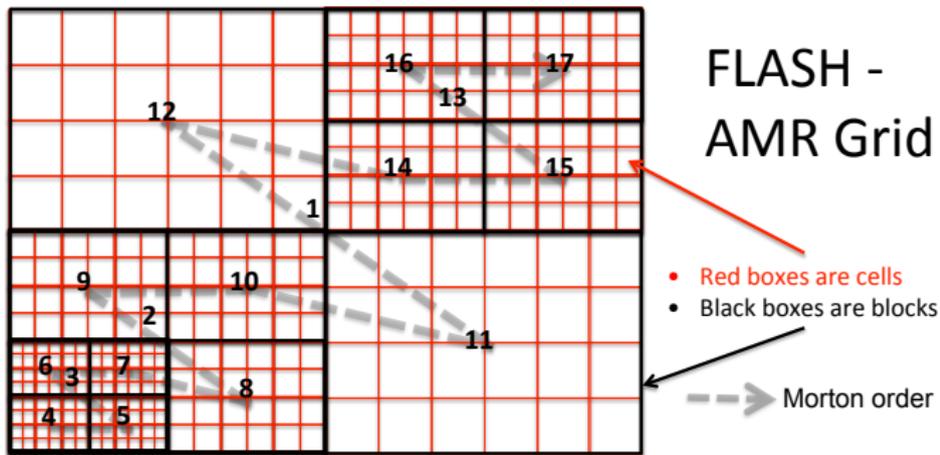
HDF5: Potential for odd interactions between application data layout and chunk allocation



Lower-triangular aware storage mode and layout



Example: FLASH



Example: FLASH

- Parallel adaptive-mesh refinement (AMR) code; Block structured - a block is the unit of computation
- **Tree information:** FLASH uses tree data structure for storing grid blocks and relationships among blocks, including lrefine, which_child, nodetype and gid.
- **Per-block metadata:** FLASH stores the size and coordinates of each block in three different arrays: coord, bsize and bnd_box
- **Solution Data:** Physical variables i.e. located on actual grid are stored in a multi-dimensional (5D) array e.g. UNK



Goals

- Provide higher-level data model API to describe more sophisticated data models
- Enable exascale computational science applications to interact conveniently and efficiently with storage through the data model API
- Develop a data model storage library to support these data models, provide efficient storage data layouts
- Productizing Damsel and working with computational scientists to encourage adoption of this library by the scientific community

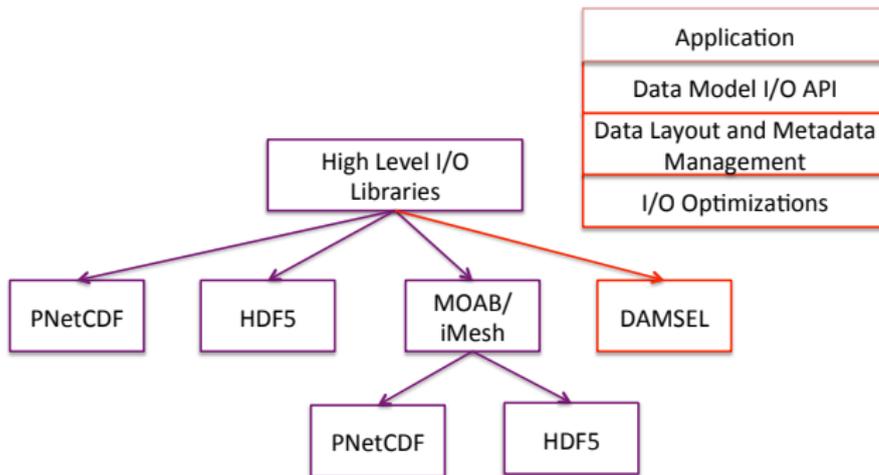


2 Damsel I/O Library

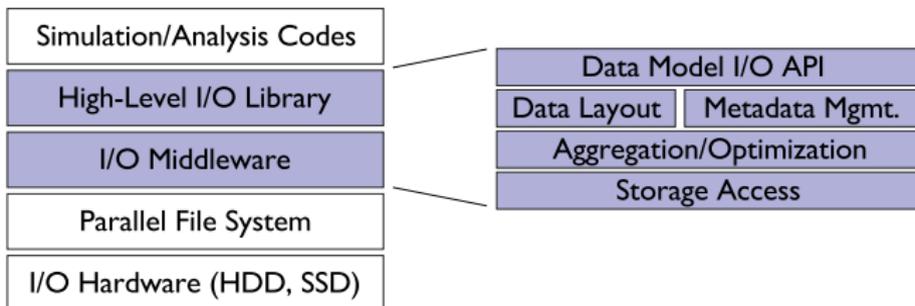
- Introduction
- Data Model



Big Picture



Proposed Approach



Proposed Approach

- a set of data models I/O APIs relevant to computational science applications
- a data layout component that maps these data models onto storage efficiently,
- a rich metadata representation and management layer that handles both internal metadata and that generated by users and external tools,
- I/O optimizations: adaptive collective I/O, request aggregation, and virtual filing,

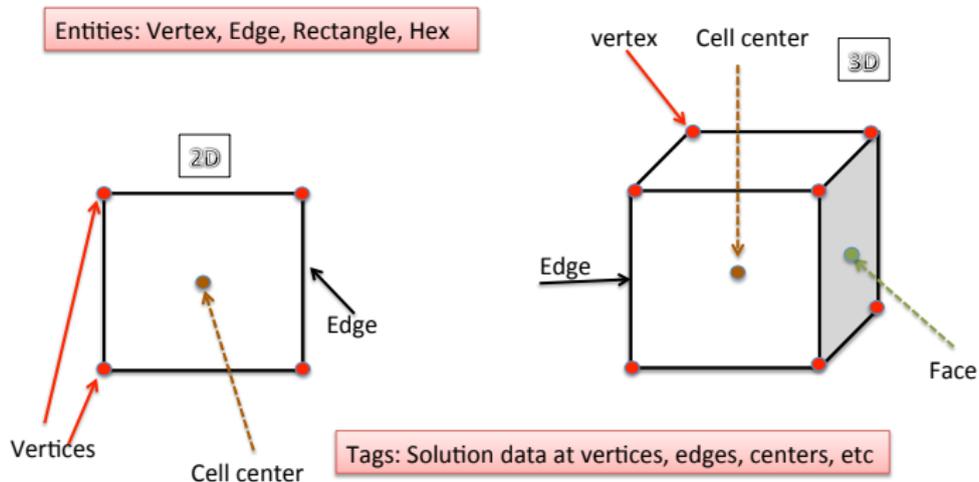


Data Model Components

- Describe structural/(hierarchical) and solution information through API
- To describe the structural information, i.e. Grid data
Entity, Entity sets, Structured Blocks
- To describe the solution variable, i.e. Solution data
Tags on Entities, Entity Sets, Structured Blocks

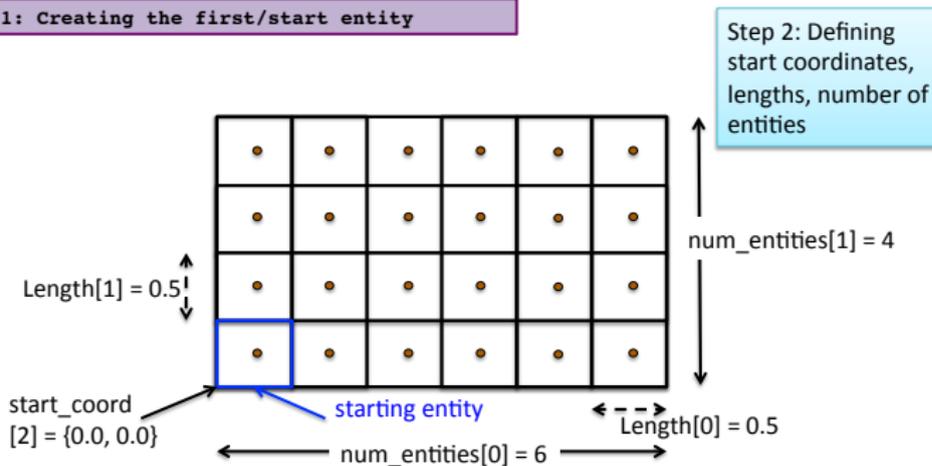


Example: Entity and Tags



Example: Blocks and Tags

Step 1: Creating the first/start entity

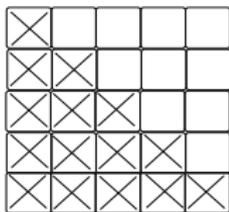


Step 3: Creating a cartesian mesh/structured block

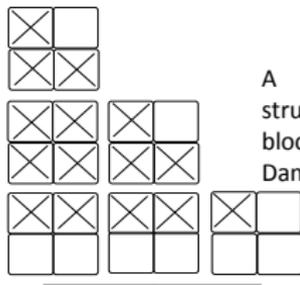
Step 4: Tag the centers of entities in cartesian mesh/structured block



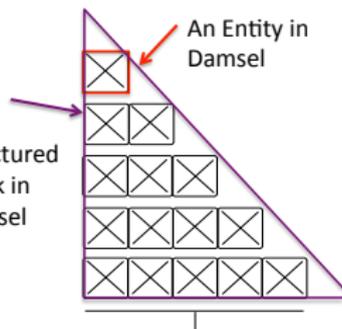
Example: Lower Triangle Matrix



netCDF: fixed dimensions



HDF5: Potential for odd interactions between application data layout and chunk allocation



Lower-triangular aware storage mode and layout

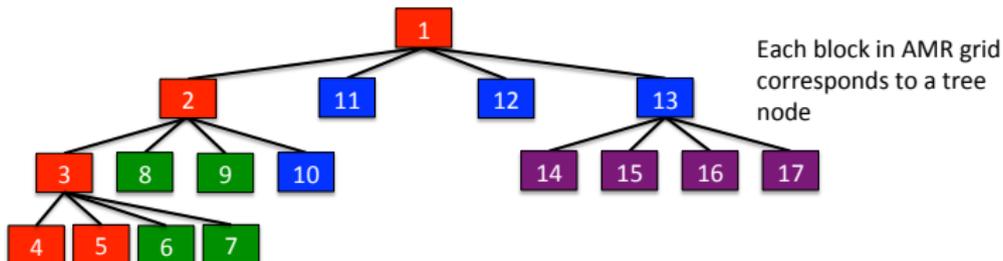
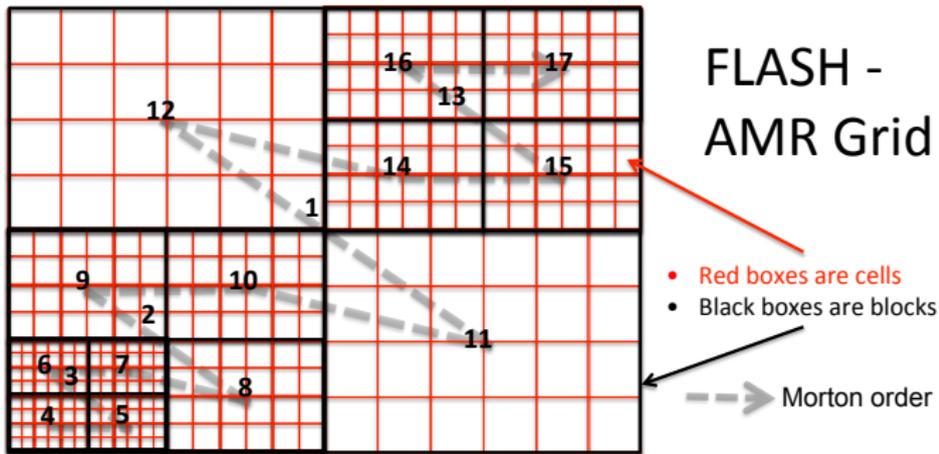


3 Usecases

- Usecase I: FLASH
- Usecase II: GCRM



Introduction



Introduction

- The FLASH is a modular, parallel multi-physics simulation code capable of handling general compressible flow problems found in many astrophysical environments.
- Parallel adaptive-mesh refinement (AMR) code; Block structured - a block is the unit of computation
- **Tree information:** FLASH uses tree data structure for storing grid blocks and relationships among blocks, including `lrefine`, `which_child`, `nodetype` and `gid`.
- **Per-block metadata:** FLASH stores the size and coordinates of each block in three different arrays: `coord`, `bsize` and `bnd_box`
- **Solution Data:** Physical variables i.e. located on actual grid are stored in a multi-dimensional (5D) array e.g. UNK



FLASH using existing I/O Libraries

FLASH in PnetCDF and MOAB

```

/*Step 1: Create data set*/
ncmpi_create_data()

/*Step 2: Define dimension*/
status = ncmpi_def_dim(ncid, "dim_tot_blocks",
(MPI_Offset)*(total_blocks), &dim_tot_blocks);

/*Step 3: Define variables*/
Status = ncmpi_def_var(ncid,
"runtime_parameters", NC_INT, rank, dimids,
&varid[id]);
status = ncmpi_def_var(ncid, "lrefine",
NC_INT, rank, dimids, &varid[id]);

/*Step 4: Create attributes for some
variables*/
status = ncmpi_put_att_int(ncid, 1,
intScalarNames[i], NC_INT, 1, &intScalarValues
[i]);

/*Step 5: Write structural & solution data*/
/* Write data from memory to file */
err = ncmpi_put_vara_all(fileID, varID,
diskStart, diskCount, pData, memCountScalar,
memType);

/*Step 6: Close the dataset/file*/
ncmpi_close(fileID);

```

```

moab::Core *mb = new moab::Core();
moab::ErrorCode rval;
moab::Range blk_handles;
moab::Tag unkTH, lrefineTH, scalarsTH;

/*Step 1: Create an Entity Set*/

/*Step 2: Define/set tags for total_blocks,
runtime parameters, etc on the Entity set*/

/*Step 3: Create FLASH blocks as vertices in
MOAB*/
rval = mb->create_vertices ( block_coords,
total_blocks, blk_handles);
if (MB_SUCCESS != rval) return 1;

/*Step 4: Define tags for the structural
information per block and solution data*/
rval = mb->tag_create("lrefine", sizeof(int),
MB_TAG_DENSE, lrefineTH, lrefine);
rval = mb->tag_create("unk", 10*(nxb*nyb*nzb)
*sizeof(double), MB_TAG_DENSE, unkTH, unk);

/*Step 5: Set tags for tree & solution data*/
rval = mb->tag_set_data(lrefineTH, blk_handles,
lrefine);
rval = mb->tag_set_data(unkTH, blk_handles,
unk);

/*Step 6: HDF5 File I/O*/
/* Write data from memory to file */

```



FLASH using DAMSEL

- Goal: to describe hierarchical/structural and solution information through API
- Entity
 - Cells as Rectangles
 - Blocks as Cartesian Mesh
- Entity Sets
 - Blocks assigned to entity sets to define hierarchical/structural information
- Tags
 - Only for solution data



FLASH using proposed DAMSEL API

Step 1: Creating the first/start entity

```
damsel_create_entity();
```

Step 2: Defining start coordinates, lengths, number of entities

Step 3: Creating a cartesian mesh/structured block

```
damsel_cartesianmesh_create()
```

Step 4: Defining hierarchy using Entity sets

```
damsel_create_entityset()
```

```
damsel_addEntities()
```

```
damsel_addChildren(EntityHandle , EntityHandle Children  
[])
```

Step 5: Define and set tags

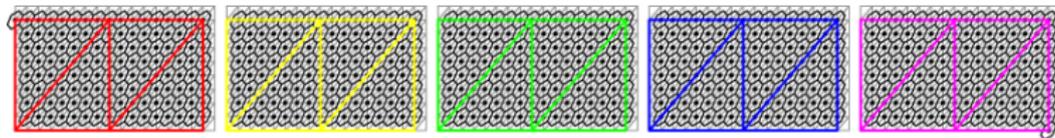
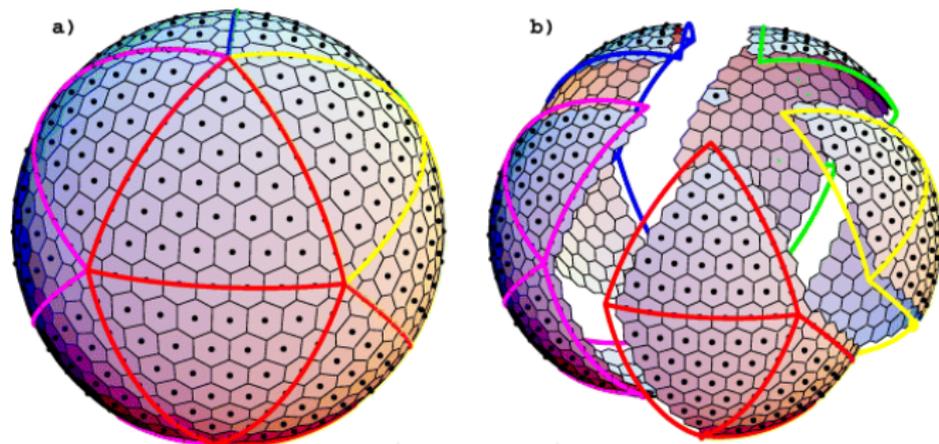
```
damsel_tag_define()
```

```
damsel_tag_setval()
```

Step 6: Damsel I/O

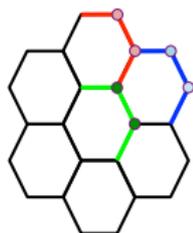


Introduction



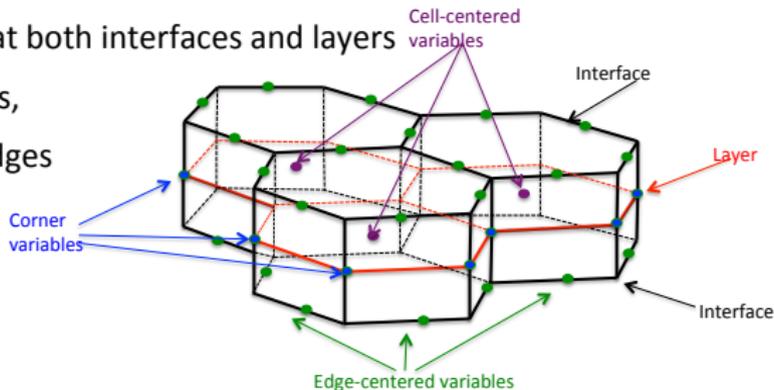
Introduction

- Grid data
 - Cell corners (2/cell)
 - Cell edges (3/cell)
 - Layers and interfaces



- Solution data at both interfaces and layers

- Cell centers,
- corners, edges



GCRM using existing I/O Libraries

PNetCDF

- Grid Data:
 - Dimensions: Cells, edges, interfaces, etc
 - Variables: `grid_center_lat(cells)`, `grid_corner_lat(corners)`, `cell_corners(cells, cellcorners)`
- Solution Data:
 - float `pressure(time, cells, layers)`
 - float `u(time, corners, layers)`
 - float `wind(time, edges, layers)`

MOAB

- A Hexagonal Prism entity to describe a cell
- An unstructured mesh to describe GCRM grid (no hierarchical information)



GCRM using DAMSEL

- A Hexagonal Prism entity to describe a cell
- An unstructured mesh to describe GCRM grid (no hierarchical information)
- Or a structured mesh to describe GCRM grid



Summary

- Motivation
- DAMSEL Data Model
- Usecases: FLASH and GCRM
- API Implementation and data layout work is in progress

